Degree project

A Non-functional evaluation of NoSQL Database Management Systems

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Abstract

NoSQL is basically a family name for all Database Management Systems (DBMS) that is not Relational DBMS. The fast growth of all social networks has led to a huge amount of unstructured data that NoSQL DBMS is supposed to handle better than Relational DBMS. Most comparisons performed are between Relational DBMS and NoSQL DBMS. In this paper, the comparison is about non-functional properties for different types of NoSQL DBMS instead. Three of the most common NoSQL types are Document Stores, Key-Value Stores and Column Stores. The most used DBMS of those types are MongoDB, Redis and Apache Cassandra. After working with the databases and performing YCSB Benchmarking the conclusion is that if the database should handle an enormous amount of data, Cassandra is most probably best choice. If speed is the most important property and if all data fits within the memory; Redis is probably the most well suited database. If the database needs to be flexible and versatile, MongoDB is probably the best choice.
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1 Introduction

This chapter gives a brief summary of NoSQL databases along with existing research regarding the subject. It will also mention the limitations and the research questions for this thesis project.

1.1 Introduction/Background

NoSQL (usually interpreted as Not only SQL) Data Base Management Systems (DBMS) are a relatively new kind of databases. NoSQL DBMS are increasingly used, but Relational DBMS (RDBMS) are still dominating the market. Over 90% of all systems are using RDBMS [1].

NoSQL is basically a family name for all DBMS that is not RDBMS. The main reason for the need to invent NoSQL DBMS is the fast growth of all social networks, which has led to a huge amount of unstructured data that NoSQL is supposed to handle better than RDBMS. NoSQL DBMS are supposed to be more scalable and take advantage of new nodes and clusters without the need of additional management.

NoSQL can infer a lot of different types of databases. Three of the most common NoSQL types are Document Stores, Key-Value Stores and Column Stores [2]. The most used DBMS of the types are MongoDB, Redis and Apache Cassandra. Those are the databases that will be looked at in this article.

1.2 Previous research

Most benchmarks and comparisons of different DBMS are performed between different kinds of Relational DBMS [3]. In some cases benchmarks are performed between Relational databases and NoSQL DBMS, but not by the most used NoSQL DBMS types [4]. The benchmarks that have been performed between different NoSQL DBMS are mainly focused on functional requirements [5]. This article focuses benchmarking on non-functional properties of the most popular NoSQL DBMS of the most used NoSQL types, along with a few functional requirement benchmarks. The properties chosen to be benchmarked are based on what is most of interest to computer related companies.
1.3 Purpose and research question/hypothesis

<table>
<thead>
<tr>
<th>RQ1.</th>
<th>Which is the set of non-functional properties of interest for industry?</th>
</tr>
</thead>
<tbody>
<tr>
<td>RQ2.</td>
<td>Based on RQ1 properties; which is the most versatile NoSQL DBMS?</td>
</tr>
</tbody>
</table>

Since NoSQL DBMS are becoming more popular, it would be interesting to understand the set of non-functional properties to take into account when selecting among the NoSQL DBMS products available on the market.

1.4 Scope/limitation

The non-functional properties that will be investigated in the article are the following:

- Efficiency – Find out which database are the most effective in terms of CPU- and memory usage.
- Performance – Perform benchmarks measuring the time of inserting, finding and deleting data.
- Usability – Discover which one of them that is most user-friendly and easiest to set up.
- Flexibility – Find out which one that is easiest to upgrade and extend.
- Availability – Manageability, recoverability, reliability, serviceability [6].

The research will be limited to three different NoSQL DBMS. The most popular NoSQL DBMS types are Document stores, Key-value stores and Column stores [2]. The most used Document store is MongoDB, Redis is the most used Key-value store and the most popular Column store is Cassandra. Those three NoSQL DBMS will be used in this thesis project.
2 Background/Theory

This chapter contains information about all major technologies and terms that have been involved in this thesis project. Firstly, a brief summary of RDBMS, followed by a summary of NoSQL DBMS. The NoSQL summary goes more into details about different NoSQL types and especially about the databases that are used in the benchmarks described in the Result chapter. The ACID, BASE and CAP theorems are also described in this chapter.

2.1 Relational Database Management Systems

This is by far the most popular kind of database management systems. According to the dbengines website, the three most used DBMS are RDBMS [2]. They are the “old” kind of databases where tables consist of rows and columns and each column has a specified type. Information is stored once for each column. A row only contains values for record, no type information. All rows in a table have the same columns and are homogenous. A RDBMS must read the entire row in order to access the requested column data, which many times lead to an unnecessary amount of reads. That in mind - RDBMS generally still performs faster reads than writes. Figure 2.1 shows a typical row in a RDBMS.

<table>
<thead>
<tr>
<th>Username (String)</th>
<th>First_name (String)</th>
<th>Last_name (String)</th>
<th>Gender (String)</th>
<th>Age (Integer)</th>
</tr>
</thead>
<tbody>
<tr>
<td>JohanL</td>
<td>Johan</td>
<td>Landbris</td>
<td>Male</td>
<td>25</td>
</tr>
</tbody>
</table>

Figure 2.1: Displaying a typical row in a RDBMS.

2.1.1 ACID Acronym – Relational DBMS properties

RDBMS generally follow the ACID acronym. In theory, each letter is essential. For a very long time, all webpages were able to handle the traffic with RDBMS and the ACID acronym. However, they lack in availability and performance when handling huge amount of data [7].

- **Atomic:** Everything in a transaction succeeds or everything fails. All or nothing rule.
- **Consistent:** A transaction cannot leave the database in an inconsistent state. Everything is always in order in the database and it never
violates any rules – the database is consistent both in the beginning and in the end of a transaction. Only valid data will be written to the database. If a transaction violates the consistency rules, the transaction will not go through and the database will be restored to a previous state without any failures – a consistent state.

- **Isolated**: Transactions cannot interfere with each other. Every transaction is completely independent.
- **Durable**: A completed transaction persists even when servers restart, system failures or power loss etc.

2.2 NoSQL

NoSQL (usually interpreted as Not only SQL) Data Base Management Systems are a relatively new kind of databases. One definition of NoSQL is “Different NoSQL databases take different approaches. What they have in common is that they’re not relational. Their primary advantage is that, unlike relational databases, they handle unstructured data such as word-processing files, e-mail, multimedia, and social media efficiently” [8]. However, since NoSQL DBMS comes in so many different shapes, it is hard to give a general definition. NoSQL is basically a family name for all DBMS that is not RDBMS. The main reason for the need to invent NoSQL DBMS is the fast growth of all social networks, which has led to a huge amount of unstructured data that NoSQL is supposed to handle better than RDBMS. NoSQL DBMS are supposed to be more scalable and take advantage of new nodes and clusters without the need of additional management. NoSQL should therefore be cheaper to maintain than RDBMS, both because of less management and the horizontal scalability with many cheaper servers instead of a few expensive servers.

2.2.1 History about NoSQL

The term NoSQL was first used in 1998 by Carlo Strozzi [9]. He had an open source project which did not offer an ordinary SQL interface. He called his database “NoSQL” and stored all data as ASCII files which was a first step towards something else than RDBMS. This, however, does not have anything to do with today’s NoSQL RDBMS. The term has no scientific accepted definition since it is such a broad term.
2.2.2 BASE Acronym – NoSQL properties

The BASE acronym is usually used to describe properties of NoSQL databases. It has some similarities to the ACID acronym which instead is used to describe Relational DBMS properties. See the ACID Acronym – Relational DBMS properties chapter (2.1.1) for differences between the two acronyms.

- **Basic Availability**: The system does guarantee the availability of the data - every request will be answered. Even if the database has multiple failures, it should be available. NoSQL DBMS usually spreads data to multiple storage systems and therefore the fault tolerance is spread. Even if one event fails the fault handling is performed in that specific data store and the whole system does not go down and is still available.
- **Soft-state**: The system state may change over time, even without any operation performed, therefore – the system state is always soft.
- **Eventual consistency**: The system will eventually be consistent once it stops receiving input. Consistency infers that a transaction cannot leave the database in an inconsistent state. Everything is always in order in the database and it never violates any rules – the database is consistent both in the beginning and in the end of a transaction. Only valid data will be written to the database. If a transaction violates the consistency rules, the transaction will not go through and the database will be restored to a previous state without any failures – a consistent state.

2.2.3 CAP Theorem

The CAP theorem explains the theoretical gap between ACID and BASE compliant databases and it claims that it is impossible for a database to be all three letters [10].

- **Consistency**: A transaction cannot leave the database in an inconsistent state. Everything is always in order in the database and it never violates any rules – the database is consistent both in the beginning and in the end of a transaction. Only valid data will be written to the database. If a transaction violates the consistency rules, the transaction will not go through and the database will be restored to a previous state without any failures – a consistent state.
- **Availability**: The given system is available when needed – there will always be a response to any request.
Partition Tolerance: A system should continue to operate even when there is partial data loss, temporary system failure or interruption. A single node failure should not cause the system to stop working. No failure other than total network failure is allowed to cause the system to behave differently.

2.2.4 Clustering

A big difference between NoSQL DBMS and RDBMS is that NoSQL generally cluster much easier, which is a very common requirement in most large systems these days. In context of databases, clustering infers that many instances or servers connect to the same database. A major advantage with clustering is the fault tolerance, since there are several servers or instances running. If one server or instance is shut down, a user can connect to one of the servers or instances still running. Another advantage is that a cluster in general connects a user to the server or instance with the least load at the connecting moment.

2.2.5 Key-value store

Key-value stores are often described as the simplest version of a NoSQL DBMS. It stores records in only two columns. One column contains the key, often stored as a string. The other column contains the value, the actual data. The user can only access the value if the Key is known. It is not possible the other way around – trying to find the Key by knowing the Value. The data or value often consists of a primitive such as a string or integer. Figure 2.2 shows a typical Key-value relation.

Key  
---
car1_seats 5  
car1_color Green  
car5_year 1994  
car5_color Blue  
car1_year 2003  
car44_seats 5  
car44_year 2011

Figure 2.2: Describing a basic example of a Key-value relation.

The “car” and a number is the only common part for each key. Three properties are mentioned in this example – seats, color and year. Each car
does not have to store every property and no primary key. There are many different key-value stores on the market and they work a bit differently. This is however a basic explanation that applies to most of them. Redis is an open-source key-value database created by Salvatore Sanfilippo in 2009 [11]. The company started with a few sponsors along with donations, but it is now sponsored by Pivotal. Redis is now by far the most used key-value store [12]. Redis is an in-memory key-value store. A major difference between Redis and many other key-value stores is that Redis can handle a large number of different datatypes, which makes it very versatile. The value can for example, along with primitive datatypes, also consist of lists, hashes or sets. Redis handles the whole dataset in memory until data is written to disc asynchronously. The administrator can decide how often Redis should save the data from memory to disc. If the system crashes, some of the data still in memory might get lost if it is not saved to disc. Redis is therefore considered to be a CP in the CAP theorem. Please see the BASE chapter (2.2.2), especially the BA part for more information about availability along with the CAP chapter (2.2.3). Redis supports the following languages:

- C
- C#
- C++
- Clojure
- Dart
- Erlang
- Go
- Haskell
- Java
- JavaScript
- Lisp
- Lua
- Objective-C
- Perl
- PHP
- Python
- Ruby
- Scala
- Smalltalk
- Tcl

Redis supports the following operating systems:

- BSD
- Linux
- OS X
- Windows
2.2.6 Column store

A column store has all data organized and stored in columns instead of the usual RDBMS rows. A row in a column store has some kind of row id, where each column value is associated with each other. Instead of searching each row, column stores only focus on the column that is of interest. That is, in theory, faster than a row store. An example: A database has 10,000 users, which equals 10,000 rows, one for each user. If the user wants Username and Gender for a user, a row store must search each column for each row, which can be up to 10,000x5=50,000 column values. Figure 2.3 shows a typical row in a row store.

<table>
<thead>
<tr>
<th>Username</th>
<th>First_name</th>
<th>Last_name</th>
<th>Gender</th>
<th>Age</th>
</tr>
</thead>
<tbody>
<tr>
<td>JohanL</td>
<td>Johan</td>
<td>Landbris</td>
<td>Male</td>
<td>25</td>
</tr>
</tbody>
</table>

Figure 2.3: Displaying a typical row in a row store.

If the same search is performed in a column oriented store, the maximum column values that can be looked into are 10,000x2=20,000 since column stores only focus on the columns that are relevant. Figure 2.4 highlights the difference between a row store and a column store.

<table>
<thead>
<tr>
<th>Username</th>
<th>First_name</th>
<th>Last_name</th>
<th>Gender</th>
<th>Age</th>
</tr>
</thead>
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<td>Johan</td>
<td>Landbris</td>
<td>Male</td>
<td>25</td>
</tr>
</tbody>
</table>

Figure 2.4: Highlighting the relevant columns in a column store.

Apache Cassandra is a combination of Google Bigtable and Amazon Dynamo that was incubated in Facebook. In July 2008 Cassandra became an open-source and in March 2009 Cassandra became an Apache project [13]. Cassandra is a peer-to-peer distributed system with nodes, where data is distributed to all nodes within the cluster. All nodes are the same and equal in Cassandra, meaning there is no central master node. Data is partitioned among all nodes in a cluster. Each node communicates with each other and exchanges information across the cluster every second, which is referred to as a gossip protocol. A collection of all related nodes are called Data center. A column family is a container with a collection of rows. Every row contains columns which are in order. Column families represent the structure of the data. New nodes can be added to the Cassandra cluster without the need to shut down the system. Cassandra satisfies Availability and Partition tolerance (AP) according to the CAP theorem, since data is not written to disc until the Mem-Table is full. See the CAP chapter (2.2.3) for a more detailed explanation. Cassandra writes data to disc in the following sequence:
1. Commit log: Data is first written to a commit log, where all data is saved as a backup if the system should crash.

2. Node: Data is sent to an appropriate Node. When the node gets the data it saves it in a local log and sends it to the correct mem-table for the column family.

3. Mem-table: In-memory temporarily storage for Cassandra, works a lot like key-value pairs. When the memory is full or when time is up (decided by the user), the mem-table is flushed to disc, SSTable.

4. SSTable (Stored String Table): SSTable is the disc store for Cassandra. Cassandra makes sure data ends up in the correct SSTable with help of a Bloom filter.

5. Bloom filter: Bloom filters basically test whether the incoming data is a member of this set or SSTable. Bloom filter is also used for read requests. The filter checks the probability for a SSTable to contain the requested data.

6. When all column families from the Commit log are pushed to disc, they are deleted.

7. Compaction: Cassandra can free disc space by merging large accumulated data files. Data is indexed, sorted, merged and collected from many old SSTables into a new SSTable. This makes scan time a lot faster.

Cassandra reads data from disc in the following sequence:

1. Cassandra checks the Bloom filter, which decides the probability for the SSTable to contain the requested data.

2. If the probability/chance is good, Cassandra looks at the partition key cache which is a cache of the partition index which is a list of primary keys and start position of data, for tables.

If an index entry is found in cache: The compression map is used to find the block containing the data. The requested data is merged from all SSTables, or if the data is found in the mem-table, for faster future reads and is returned.

If an index entry is not found in cache: Cassandra searches the partition summary, a subset of the partition index, to determine the approximate disc location of the index entry. Depending on the results from the partition summary, Cassandra performs a sequential read of columns in the SSTables of interest. Correct data is merged and returned. Cassandra supports the following languages:
C
C#
C++
Clojure
Erlang
Go
Haskell
Java
JavaScript
Perl
PHP
Python
Ruby
Scala

Cassandra supports the following operating systems:
- BSD
- Linux
- OS X
- Windows

2.2.7 Document store

Document stores or document-oriented databases are one of the most common NoSQL types along with Column store, Key-value store and Graph store. They are in some ways a sub category of Key-value stores since each document is recognized with a key. Document stores contain, as the name reveals, documents. All data is stored in the document itself and is totally schema-free without tables, row or columns. Each document is totally independent from the others. This makes document-oriented databases flexible. They can simply add or delete a field from a document without disturbing other documents. In contrast to relational database management systems there is no need to have any empty fields. Common document encodings are for example JSON, BSON and XML.

MongoDB was developed in 2007 by 10gen and was available as open source in 2009 with the possibility for a commercial license [14]. MongoDB has a flexible schema, in contrast to most relational databases where the developer must decide the schema for each table before any data is inserted. Instead of tables, MongoDB uses collections. A collection is a group of documents, but documents within the collection can still have different fields. Documents in a collection usually fill the same purpose though. MongoDB documents are stored in BSON format, which is a binary version of JSON documents. BSON can contain more data types than JSON. Documents can be linked or referenced to each other with a key. Embedded
documents are an alternative to references, where all information is embedded in a single document instead of using references to many documents. Generally, embedded documents provide better performance but reference documents are more flexible. Figure 2.5 shows relationships with references between documents and Figure 2.6 shows embedded documents relationships.

Figure 2.5: Displaying relationships with references between documents [15].

Figure 2.6: Displaying embedded document relationship [15].
MongoDB supports the following languages:

- Actionscript
- C
- C#
- C++
- Clojure
- ColdFusion
- D
- Dart
- Delphi
- Erlang
- Go
- Groovy
- Haskell
- Java
- JavaScript
- Lisp
- Lua
- MatLab
- Perl
- PHP
- PowerShell
- Prolog
- Python
- R
- Ruby
- Scala
- Smalltalk

MongoDB supports the following operating systems:

- Linux
- OS X
- Solaris
- Windows
3 Method

This chapter describes the approach throughout the whole thesis project, along with some specific technical solutions.

3.1 Scientific approach

To discover which non-functional properties for databases that was most important for companies, a survey was sent out to computer related companies. Phone interviews were conducted with people working at different computer related companies. YSCB (Yahoo! Cloud Serving Benchmark) was used to benchmark the non-functional properties based on the survey and interview answers.

3.2 Human centered approach

The information about which non-function properties that should be benchmarked and used as the base for this research was decided from a survey along with interviews with computer related companies.

3.2.1 Survey

The survey was sent as a link to 20 companies. It was created and handled online with the help of a webpage, SurveyMonkey[16]. All survey answers were anonymous. Figure 3.1 shows the survey sent out to companies.
3.2.2 Interviews

The interviews conducted were over phone with 6 of the companies that was originally being sent the survey. The questions asked during the interviews were based on the survey. All interview answers were anonymous.
3.3 Yahoo! Cloud Serving Benchmark (YCSB)

Since NoSQL DBMS still are quite new, there are not that many good and fair benchmarking tools. There are, however, a lot of existing benchmarking tools for RDBMS but they are, for obvious reasons, not compatible with NoSQL DBMS. Most of the existing NoSQL tools are either provided by the database company itself, or not compatible with different NoSQL types. It is hard to develop a benchmarking tool for all NoSQL types (See the Column Store (2.2.5), Key-value Store (2.2.4) and Document Store (2.2.6) chapters for additional information about the differences in NoSQL DBMS). The Yahoo! Cloud Serving Benchmark was chosen for this project, since it is the most fair, independent and versatile choice.

Yahoo! Cloud Serving Benchmark is not very useful by itself, but it provides a good framework for benchmarking NoSQL DBMS [17]. The YCSB client is a generator of workloads. YCSB provides a few typical workloads for the most common operations for a DBMS. Basically, the YCSB client generates a workload. The workload could be one of the core workloads pre-defined by YCSB or the user can create a customized workload. The YCSB client is connected to an interface layer of client code for the DBMS of the user’s choice. A workload is then run through the YCSB client and is connected to the chosen database server. Here follows a description of each workload:

- **Workload A** - Update heavy workload: This workload has a mix of 50/50 reads and writes. An application example is a session store recording recent actions.
- **Workload B** - Read mostly workload: This workload has a 95/5 reads/write mix. Application example: photo tagging; add a tag is an update, but most operations are to read tags.
- **Workload C** - Read only: This workload is 100% read. Application example: user profile cache, where profiles are constructed elsewhere (e.g., Hadoop).
- **Workload D** - Read latest workload: In this workload, new records are inserted, and the most recently inserted records are the most popular. Application example: user status updates; people want to read the latest.
- **Workload E** - Short ranges: In this workload, short ranges of records are queried, instead of individual records. Application example: threaded conversations, where each scan is for the posts in a given thread (assumed to be clustered by thread id).
- **Workload F** - Read-modify-write: In this workload, the client will read a record, modify it, and write back the changes. Application
example: user database, where user records are read and modified by the user or to record user activity.

4 Results/Analysis

This chapter displays results from the surveys and interviews along with YCSB benchmark results.

4.1 Survey

Figure 4.1 shows a diagram with survey and interview answers from computer related companies. The question asked is “How important are the following non-functional properties when deciding database?”. Rating 1 infers not important and rating 5 infers important.

![Survey and interviews](image)

*Figure 4.1: Survey and interviews.*

The survey displayed that according to the companies: Dependability (availability, manageability, recoverability, reliability, serviceability) was the most important non-functional property, followed by Performance (access time - Create, Read, Update, and Delete data) and Efficiency (CPU- and memory load).
4.2 Interviews

The interviews were conducted over phone and they gave a more versatile picture of the non-functional properties of interest. They generated very different responses depending on the database size and what the database was used for. Some companies with different databases had different non-functional property ranking for each database. However, in general the result was very similar to the Survey answers.

4.3 YCSB benchmarking

Technical specification for the computer used when performing YCSB benchmarking:

CPU: Intel Core i5 3570k, 3.4 Ghz
Harddrive: Seagate Barracuda ST1000DM003 1TB 7200 RPM
Memory: 8 GB DDR3 1600MHz
Operating system: Ubuntu 14.04.2 LTS

4.2.1 Workload

Figure 4.2 shows results for Workload A – 50 % reads, 50 % writes.

![Figure 4.2: Workload A – 50 % reads, 50 % writes.](image)
Figure 4.3 shows results for Workload B – 95% reads, 5% writes.

![Figure 4.3: Workload B – 95% reads, 5% writes.](image)

Figure 4.4 shows results for Workload C – 100% reads.

![Figure 4.4: Workload C – 100% reads.](image)
Figure 4.5 shows results for Workload D – Read latest workload.

![Workload D](image)

Figure 4.5: Workload D – Read latest workload.

Figure 4.6 shows results for Workload F – Read-modify-write.

![Workload F](image)

Figure 4.6: Workload F – Read-modify-write.
Redis benchmark results for Workload A (50% reads and 50% writes), is better than Workload B (95% reads and 5% writes) and Workload C (100% reads). Redis therefore generally writes faster than it reads. The reason for this is because Redis initially only writes to the memory. Redis handles the whole dataset in memory until data is written to disc asynchronously. The administrator decides how often Redis should save the data from memory to disc. When performing a read on the other hand, Redis sometimes needs to look for data on disc if it is not found in memory.

In Workload A (50% reads and 50% writes), Cassandra is performing better than Workload B (95% reads and 5% writes) and Workload C (100% reads). It means that Cassandra writes data faster than it reads. This was never the case when dealing with traditional SQL databases since they are implemented differently that Cassandra. When writing, Cassandra first writes all data to memory until it is full and flushed to disc. Reads on the other hand almost always need access the permanent disc storage, SSTable, along with searching the memory storage, mem-table (See chapter 2.2.6 Column store for more information about the Cassandra write/read sequence). In Workload D (Read latest workload) Cassandra performs very well since in most cases it has to read from the mem-table since the mem-table most likely has not yet been flushed to disc.

MongoDB benchmark shows that Workload B (95% reads and 5% writes) and Workload C (100% reads) outperforms Workload A (50% reads and 50% writes). MongoDB therefore reads way faster than it writes much like a traditional RDBMS. Even benchmark results from Workload D (Read latest workload) outperforms Workload A (50% reads and 50% writes).

Redis is the fastest of the three in almost all cases besides Workload D where Cassandra is a bit faster. MongoDB is the slowest in all cases besides Workload F where Cassandra is the slowest.
4.2.2 CPU Load

Figure 4.7 shows results for average CPU load.

![Average CPU Load](image.png)

Figure 4.7: CPU Load – Average CPU Load.

Redis’s CPU load was around 55% for each benchmark, way lower than both Cassandra and MongoDB. The reason is probably because of its in-memory approach. Cassandra’s average CPU load was around 88% and average CPU load for MongoDB was about 85% throughout all benchmarks.
4.2.3 Memory Load

Figure 4.8 shows results for average memory load.

![Average Memory Load](image)

*Figure 4.8: Memory load – Average memory load.*

Redis’s memory load was about 25% for each benchmark. It was much higher than both Cassandra’s and MongoDB’s. Just as the CPU load, the reason is probably because its in-memory approach. For Cassandra, memory load was a bit higher when writing than reading with an average of around 14%. MongoDB had an average memory load on about 18% for each benchmark.
5 Discussion

This chapter analyzes and discusses the results displayed in chapter 4 – Results/Empirical data. It also includes a reflection regarding method choices throughout the thesis project.

5.1 Problem solving/results

Redis turned out to be the fastest, quite far ahead of the other two in almost every benchmark. Cassandra was often the second fastest and MongoDB the slowest. Redis Memory load was the highest and its CPU load was the lowest. Cassandra and MongoDB were quite equal in both CPU load and Memory load.

The reason for Redis's outstanding speed is probably because Redis is less complicated than the other two since it is a Key-value store (See chapter 2.2.5 for more information about Key-value stores). Redis also handles all data in memory which makes it rapidly fast. That is why Redis's average Memory load was above Cassandra's and MongoDB's. I found Redis to be easy to both set up and work with.

Cassandra performed good in each benchmark. It is not the best but not the worst either. Cassandra's main advantage over the other two databases is its scalability and clustering possibilities. A Cassandra cluster scales linearly and is relatively easy to set up. However, Cassandra is the most difficult to work with and it is quite hard to make changes to it. It is very different in both setup and commands compared to traditional relational DBMS’s.

MongoDB performed the worst in almost every benchmark. The main advantage of MongoDB is its flexibility. Each document could have completely different fields even within the same collection, which makes it very versatile (See chapter 2.2.7.1.1 for more information about MongoDB Function). I found MongoDB to be the easiest to work with, since it reminds a lot of Relational DBMS. MongoDB scales well, but not as good as linearly.

In one sense Redis, Cassandra and MongoDB are very similar since they after all are databases that handle and stores data. When looking closer, they are however very different. I could recommend all three databases, totally depending on the usage. If the database should handle an enormous amount of data, Cassandra is most probably the way to go. However, very few applications and systems are in need for such large amount of data that it should be worth it. If speed is the main thing, Redis is probably the most well suited choice if the operations are not too advanced and the database size can fit within the memory. If the database needs to be
flexible and not really sure how it should be designed or how big it will be, MongoDB is probably a good choice.

Since each database is best suited for some specific tasks, one common option in bigger systems is to combine different database types within the same system where each database is best suited for its specific task. When choosing database the CAP theorem (see chapter 2.2.3) can also be considered, were Redis and MongoDB is considered to be CP and Cassandra is AP.

In almost every case, MongoDB is a good choice. It is easy to use and understand and it is relatively fast even though it is slower than Cassandra and Redis. It is also flexible and scales quite well. Average-sized systems very seldom need the speed of Redis or the scalability of Cassandra, so in these cases MongoDB is the most versatile NoSQL DBMS of the three. But, once again, it completely depends on the situation.

5.2 Method reflection

I should have asked more companies to get a clearer picture of what non-functional properties that was of interest. Since only 7 companies responded the survey and 6 interviews were conducted, the answer may not be totally reliable.

I would also have liked to perform a few benchmarks using clusters, since that is the case in many big companies. This is however not very easy considering the limited time and resources for a thesis project. Overall I am relatively pleased with my choice of method.
6 Conclusion

This chapter gives a brief summary of the conclusion of the thesis project. It also suggests further research regarding similar research area.

6.1 Conclusions

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<tr>
<th>RQ1.</th>
<th>Which is the set of non-functional properties of interest for industry?</th>
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<tbody>
<tr>
<td>RQ2.</td>
<td>Based on RQ1 properties; which is the most versatile NoSQL DBMS?</td>
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Research question 1 is not answered since the survey and interviews did not generate enough answers from computer related companies.

Research question 2 is answered, but since the question is based on research question 1, the answer is a bit subjective. Cassandra is most probably the best choice if the database should handle an enormous amount of data. Redis is probably the most well suited database if speed is the most important property and if all data fits within the memory. MongoDB is probably the best choice if the database needs to be flexible and versatile.

6.2 Further Research

I am suggesting performing benchmarks using clusters for each database. To find out if it is easily done and if it scales well without too much loss in performance and usability.
References


